



**VVLAI**

山东未来机器人有限公司  
SHANDONG FUTURE ROBOT CO.,LTD

## VP08 ROV 系统技术规格书

**VP08 ROV System technical specification**



# 1 水下机器人 Underwater Robot

Basic Specification 基本参数	
Power System 电源系统	220VAC, 50Hz, 3.5kW
ROV Depth Rating 深度等级	200msw
Robot Dimension 机器人本体尺寸 (L×W×H)	680mm×450mm×400mm
Robot Weight (in Air) 机器人本体重量(空气中)	38kg
Power Performance 动力性能	
Thruster 推进器	<ul style="list-style-type: none"> <li>1) Equipped with eight thrusters: four horizontal and four vertical.</li> <li>2) Each thruster provides a maximum forward thrust of 7.8kg.</li> <li>3) Variable speed function with 10-speed levels.</li> </ul> <p>-搭载八组推进器，其中水平四组，垂直四组            -单组推进器正向最大推力 7.8kg            -可调速</p>
Maximum Speed(still water) 最大速度 (静水)	3knots 3 节
Automatic Mode 自动模式	<ul style="list-style-type: none"> <li>-Heading hold</li> <li>-Roll/pitch hold</li> <li>- Depth hold</li> <li>-航向保持</li> <li>-横倾/俯仰保持</li> <li>-深度保持</li> </ul>
Light,camera,PTZ 照明、摄像、云台	
Light 照明	<ul style="list-style-type: none"> <li>1) Four 50W lights in the front.</li> <li>2 ) Each light provides 4000lm illumination with stepless brightness adjustment.</li> </ul> <p>-前方 4 组 50W 照明灯            -单个照明灯照度 4000lm，亮度可无级调光</p>

Camera 摄像机	<p>The PTZ carries a 2MP, 1080P HD fixed-focus digital lens with a resolution of 1920×1080P. It supports both color and black-and-white modes, with light sensitivity of approximately 0.001Lux (color) and 0.0001Lux (black-and-white), a 110°field of view, and follows PTZ rotation.</p> <p>-云台搭载 1 组 200 万，1080P 高清定焦数字镜头，分辨率 1920×1080P。具有彩色黑白双模式，光照灵敏度彩色约 0.01Lux、黑白约 0.001Lux，视角 90°，可跟随云台旋转</p>
PTZ 云台	<p>The front end of the robot is equipped with a single-axis integrated PTZ. The PTZ integrates one camera with a rotation angle of ±90°, featuring real-time position feedback.</p> <p>-1 组单轴云台，集成有摄像机，可搭载声呐 -旋转角度±90° -具有实时位置反馈功能</p>
<b>Sensor&amp;Instrument 传感器与仪器</b>	
Sensor 传感器	<p>Equipped with IMU, depth sensor, temperature sensor, water leakage detection, etc</p> <p>搭载 IMU、深度传感器、温度传感器、漏水检测等</p>
IMU	<p>-IMU integrates accelerometers, gyroscopes, and magnetometers internally</p> <p>-Heading accuracy: 0.5 ° , resolution: 0.1 °</p> <p>-Pitch accuracy: 0.1 ° , resolution: 0.1 °</p> <p>-Roll accuracy: 0.1 ° , resolution: 0.1 °</p> <p>-IMU 内部集成有加速度计、陀螺仪、磁力计</p> <p>-航向精度： 0.5° ， 分辨率： 0.1°</p> <p>-俯仰精度： 0.1° ， 分辨率： 0.1°</p> <p>-横滚精度： 0.1° ， 分辨率： 0.1°</p>
External 扩展	<p>-Reserve 3 interfaces</p>

	<p>-Can extend sonar, USBL and other components</p> <p>-预留 3 个接口</p> <p>-可扩展声呐、基线等搭载件</p>
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## 2 控制系统 Control System



### Main Technical Specification 主要技术参数

Control Box 控制箱	<ul style="list-style-type: none"><li>1) Dimension: 530mm(L) ×430mm(W) ×300mm (H) Weight: 16kg</li><li>2) Main screen: 19-inch high-brightness display with a resolution of 1920×1080P, used to display video feedback, and data from various sensors.</li><li>3) Secondary screen: 10.1-inch high-brightness display for setting robot-related parameters.</li><li>4) Processor: Intel I7。 RAM: 8GB Hard Drive: 1TB</li><li>5) Splash-proof chassis design, supports one-click video recording and snapshot capture. Equipped with a full-metal, three-proof mechanical keyboard and mouse buttons.</li></ul> <p>-尺寸: 530mm×430mm×300mm (长×宽×高)</p> <p>-重量: 16kg</p> <p>-主屏为 19 寸高亮显示屏, 分辨率 1920×1080P; 用于显示机器人反馈的视频、各个传感器等数据</p> <p>-副屏 10.1 寸高亮显示屏, 用于设置机器人相关参数</p> <p>-嵌入式工控机, 内存: 8G, 硬盘: 1T</p> <p>-采用防溅机箱设计, 可实现一键视频存储及拍照</p> <p>-采用全金属三防机械式键盘、鼠标按键</p>
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<b>Handhold Controller</b> 手持控制器	<ul style="list-style-type: none"> <li>1) The handheld controller uses a professional control handle.</li> <li>2) Controls basic robot movements, PTZ tilt motion,etc.</li> <li>3) At least two spare buttons reserved for future equipment upgrades.</li> </ul> <p>-采用专业控制手柄</p> <p>-可控制机器人的基本运动、云台俯仰动作等</p> <p>-预留至少两个备用按键供后期对设备进行升级使用</p>
<b>Control Software</b> 控制软件	<ul style="list-style-type: none"> <li>1) Multiple operating modes can be set according to different environmental conditions. During navigation, the robot can move forward, backward, turn left, turn right, strafe left/right, ascend, and descend, with multi-level speed adjustment.</li> <li>2) Supports one-click video recording and snapshot capture; adjustable lighting brightness and PTZ angle. Video overlay function allows overlay of date, time, depth, temperature, heading, etc.</li> <li>3) The software interface is fully in Chinese or English. (Language customization available)</li> </ul> <p>-可控制机器人进行前进、后退、左转、右转、左横推、右横推、上升、下降、俯仰、姿态保持、自动深度、自动航向等，速度可实现多档调节</p> <p>-可实现一键视频存储及拍照，具有视频叠加功能，可叠加日期、时间、深度、温度、航向等</p> <p>-软件采用全中文或英文界面（语言可定制）</p>

### 3 缆车 Winch



Main Technical Specification 主要技术参数	
Cable Length 线缆长度	Length: 300m. 长度: 300m。
Function 功能	-Winch: Electric slip ring winding reel -Breaking force: $\geq 300\text{kg}$ -Cable diameter: 16mm -Buoyancy: Neutral (fresh water) -The winch is equipped with four universal wheels for easy on-site use -绞车: 电滑环卷线盘 -破断拉力: $\geq 300\text{kg}$ -线缆直径: 16mm -浮力: 中性 (淡水) -绞车配置四个万向轮, 方便现场使用